

NAG Toolbox for MATLAB

f08vn

1 Purpose

f08vn computes the generalized singular value decomposition (GSVD) of an m by n complex matrix A and a p by n complex matrix B .

2 Syntax

```
[k, l, a, b, alpha, beta, u, v, q, info] = f08vn(jobu, jobv, jobq, a, b,
'm', m, 'n', n, 'p', p)
```

3 Description

The generalized singular value decomposition is given by

$$U^H A Q = D_1 \begin{pmatrix} 0 & R \end{pmatrix}, \quad V^H B Q = D_2 \begin{pmatrix} 0 & R \end{pmatrix}$$

where U , V and Q are unitary matrices. Let $(k+l)$ be the effective numerical rank of the matrix $\begin{pmatrix} A^H & B^H \end{pmatrix}^H$, then R is a $(k+l)$ by $(k+l)$ nonsingular upper triangular matrix, D_1 and D_2 are m by $(k+l)$ and p by $(k+l)$ ‘diagonal’ matrices structured as follows:

if $m - k - l \geq 0$,

$$D_1 = \begin{matrix} & k & l \\ & \begin{pmatrix} I & 0 \\ 0 & C \end{pmatrix} \\ m-k-l & \begin{pmatrix} 0 & 0 \end{pmatrix} \end{matrix}$$

$$D_2 = \begin{matrix} & k & l \\ l & \begin{pmatrix} 0 & S \\ 0 & 0 \end{pmatrix} \\ p-l & \end{matrix}$$

$$\begin{pmatrix} 0 & R \end{pmatrix} = \begin{matrix} n-k-l & k & l \\ k & \begin{pmatrix} 0 & R_{11} & R_{12} \\ 0 & 0 & R_{22} \end{pmatrix} \\ l & \end{matrix}$$

where

$$C = \text{diag}(\alpha_{k+1}, \dots, \alpha_{k+l}),$$

$$S = \text{diag}(\beta_{k+1}, \dots, \beta_{k+l}),$$

and

$$C^2 + S^2 = I.$$

R is stored in $\mathbf{a}(1:k+l, n-k-l+1:n)$ on exit.

If $m - k - l < 0$,

$$D_1 = \begin{matrix} & k & m-k & k+l-m \\ m-k & \begin{pmatrix} I & 0 & 0 \\ 0 & C & 0 \end{pmatrix} \end{matrix}$$

$$D_2 = \begin{matrix} & k & m-k & k+l-m \\ m-k & \begin{pmatrix} 0 & S & 0 \\ 0 & 0 & I \\ p-l & 0 & 0 \end{pmatrix} \\ k+l-m & \end{matrix}$$

$$\begin{pmatrix} 0 & R \end{pmatrix} = \begin{matrix} & n-k-l & k & m-k & k+l-m \\ k & \begin{pmatrix} 0 & R_{11} & R_{12} & R_{13} \\ 0 & 0 & R_{22} & R_{23} \\ k+l-m & 0 & 0 & R_{33} \end{pmatrix} \\ m-k & \\ k+l-m & \end{matrix}$$

where

$$C = \text{diag}(\alpha_{k+1}, \dots, \alpha_m),$$

$$S = \text{diag}(\beta_{k+1}, \dots, \beta_m),$$

and

$$C^2 + S^2 = I.$$

$(R_{11} \ R_{12} \ R_{13})$ is stored in **a**(1 : m , $n-k-l+1$: n) and R_{33} is stored $(0 \ R_{22} \ R_{23})$ in **b**($m-k+1$: l , $n+m-k-l+1$: n) on exit.

The function computes C , S , R and, optionally, the unitary transformation matrices U , V and Q .

In particular, if B is an n by n nonsingular matrix, then the GSVD of A and B implicitly gives the SVD of $A \times B^{-1}$:

$$AB^{-1} = U(D_1 D_2^{-1})V^H.$$

If $(A^H \ B^H)^H$ has orthonormal columns, then the GSVD of A and B is also equal to the CS decomposition of A and B . Furthermore, the GSVD can be used to derive the solution of the eigenvalue problem:

$$A^H A x = \lambda B^H B x.$$

In some literature, the GSVD of A and B is presented in the form

$$U^H A X = (0 \ D_1), \quad V^H B X = (0 \ D_2),$$

where U and V are orthogonal and X is nonsingular, and D_1 and D_2 are 'diagonal'. The former GSVD form can be converted to the latter form by taking the nonsingular matrix X as

$$X = Q \begin{pmatrix} I & 0 \\ 0 & R^{-1} \end{pmatrix}$$

4 References

Anderson E, Bai Z, Bischof C, Blackford S, Demmel J, Dongarra J J, Du Croz J J, Greenbaum A, Hammarling S, McKenney A and Sorensen D 1999 *LAPACK Users' Guide* (3rd Edition) SIAM, Philadelphia URL: <http://www.netlib.org/lapack/lug>

Golub G H and Van Loan C F 1996 *Matrix Computations* (3rd Edition) Johns Hopkins University Press, Baltimore

5 Parameters

5.1 Compulsory Input Parameters

1: **jobu** – string

If **jobu** = 'U', the unitary matrix U is computed.

If **jobu** = 'N', **u** is not computed.

Constraint: **jobu** = 'U' or 'N'.

2: **jobv** – string

If **jobv** = 'V', the unitary matrix V is computed.

If **jobv** = 'N', **v** is not computed.

Constraint: **jobv** = 'V' or 'N'.

3: **jobq** – string

If **jobq** = 'Q', the unitary matrix Q is computed.

If **jobq** = 'N', **q** is not computed.

Constraint: **jobq** = 'Q' or 'N'.

4: **a(lda,*)** – complex array

The first dimension of the array **a** must be at least $\max(1, \mathbf{m})$

The second dimension of the array must be at least $\max(1, \mathbf{n})$

The m by n matrix A .

5: **b(ldb,*)** – complex array

The first dimension of the array **b** must be at least $\max(1, \mathbf{p})$

The second dimension of the array must be at least $\max(1, \mathbf{n})$

The p by n matrix B .

5.2 Optional Input Parameters

1: **m** – int32 scalar

Default: The first dimension of the array **a**.

m , the number of rows of the matrix A .

Constraint: $\mathbf{m} \geq 0$.

2: **n** – int32 scalar

Default: The second dimension of the array **a**.

n , the number of columns of the matrices A and B .

Constraint: $\mathbf{n} \geq 0$.

3: **p** – int32 scalar

Default: The first dimension of the array **b**.

p , the number of rows of the matrix B .

Constraint: $\mathbf{p} \geq 0$.

5.3 Input Parameters Omitted from the MATLAB Interface

lda, ldb, ldu, ldv, ldq, work, rwork, iwork

5.4 Output Parameters

1: **k** – int32 scalar

2: **l** – int32 scalar

k and **l** specify the dimension of the subblocks k and l as described in Section 3; $(k + l)$ is the effective numerical rank of $(\mathbf{a}^T \ \mathbf{b}^T)^T$.

3: **a(lda,*)** – complex array

The first dimension of the array **a** must be at least $\max(1, \mathbf{m})$

The second dimension of the array must be at least $\max(1, \mathbf{n})$

Contains the triangular matrix R , or part of R . See Section 3 for details.

4: **b(ldb,*)** – complex array

The first dimension of the array **b** must be at least $\max(1, \mathbf{p})$

The second dimension of the array must be at least $\max(1, \mathbf{n})$

contains the triangular matrix R if $m - k - l < 0$. See Section 3 for details.

5: **alpha(*)** – double array

Note: the dimension of the array **alpha** must be at least $\max(1, \mathbf{n})$.

See the description of **beta**.

6: **beta(*)** – double array

Note: the dimension of the array **beta** must be at least $\max(1, \mathbf{n})$.

alpha and **beta** contain the generalized singular value pairs of A and B , α_i and β_i ;

$$\mathbf{alpha}(1 : \mathbf{k}) = 1,$$

$$\mathbf{beta}(1 : \mathbf{k}) = 0,$$

and if $m - k - l \geq 0$,

$$\mathbf{alpha}(\mathbf{k} + 1 : \mathbf{k} + \mathbf{l}) = C,$$

$$\mathbf{beta}(\mathbf{k} + 1 : \mathbf{k} + \mathbf{l}) = S,$$

or if $m - k - l < 0$,

$$\mathbf{alpha}(\mathbf{k} + 1 : \mathbf{m}) = C,$$

$$\mathbf{alpha}(\mathbf{m} + 1 : \mathbf{k} + \mathbf{l}) = 0,$$

$$\mathbf{beta}(\mathbf{k} + 1 : \mathbf{m}) = S,$$

$$\mathbf{beta}(\mathbf{m} + 1 : \mathbf{k} + \mathbf{l}) = 1, \text{ and}$$

$$\mathbf{alpha}(\mathbf{k} + \mathbf{l} + 1 : \mathbf{n}) = 0,$$

$$\mathbf{beta}(\mathbf{k} + \mathbf{l} + 1 : \mathbf{n}) = 0.$$

7: **u(ldu,*)** – complex array

The first dimension, **ldu**, of the array **u** must satisfy

$$\text{if } \mathbf{jobu} = 'U', \mathbf{ldu} \geq \max(1, \mathbf{m});$$

$$\mathbf{ldu} \geq 1 \text{ otherwise.}$$

The second dimension of the array must be at least $\max(1, \mathbf{m})$

If **jobu** = 'U', **u** contains the m by m unitary matrix U .

If **jobu** = 'N', **u** is not referenced.

8: **v(ldv,*) – complex array**

The first dimension, **ldv**, of the array **v** must satisfy

if **jobv** = 'V', **ldv** $\geq \max(1, p)$;
ldv ≥ 1 otherwise.

The second dimension of the array must be at least $\max(1, p)$

If **jobv** = 'V', **v** contains the p by p unitary matrix V .

If **jobv** = 'N', **v** is not referenced.

9: **q(ldq,*) – complex array**

The first dimension, **ldq**, of the array **q** must satisfy

if **jobq** = 'Q', **ldq** $\geq \max(1, n)$;
ldq ≥ 1 otherwise.

The second dimension of the array must be at least $\max(1, n)$

If **jobq** = 'Q', **q** contains the n by n unitary matrix Q .

If **jobq** = 'N', **q** is not referenced.

10: **info – int32 scalar**

info = 0 unless the function detects an error (see Section 6).

6 Error Indicators and Warnings

Errors or warnings detected by the function:

info = $-i$

If **info** = $-i$, parameter i had an illegal value on entry. The parameters are numbered as follows:

1: **jobu**, 2: **jobv**, 3: **jobq**, 4: **m**, 5: **n**, 6: **p**, 7: **k**, 8: **l**, 9: **a**, 10: **lda**, 11: **b**, 12: **ldb**, 13: **alpha**, 14: **beta**, 15: **u**, 16: **ldu**, 17: **v**, 18: **ldv**, 19: **q**, 20: **ldq**, 21: **work**, 22: **rwork**, 23: **iwork**, 24: **info**.

It is possible that **info** refers to a parameter that is omitted from the MATLAB interface. This usually indicates that an error in one of the other input parameters has caused an incorrect value to be inferred.

info = 1

If **info** = 1, the Jacobi-type procedure failed to converge.

7 Accuracy

The computed generalized singular value decomposition is nearly the exact generalized singular value decomposition for nearby matrices $(A + E)$ and $(B + F)$, where

$$\|E\|_2 = O(\epsilon)\|A\|_2 \text{ and } \|F\|_2 = O(\epsilon)\|B\|_2,$$

and ϵ is the *machine precision*. See Section 4.12 of Anderson *et al.* 1999 for further details.

8 Further Comments

The diagonal elements of the matrix R are real.

The real analogue of this function is f08va.

9 Example

```

jobu = 'U';
jobv = 'V';
jobq = 'Q';
a = [complex(0.96, -0.8100000000000001), complex(-0.03, +0.96), complex(-
0.91, +2.06), complex(-0.05, +0.41);
      complex(-0.98, +1.98), complex(-1.2, +0.19), complex(-0.66, +0.42),
      ...
      complex(-0.8100000000000001, +0.5600000000000001);
      complex(0.62, -0.46), complex(1.01, +0.02), complex(0.63, -0.17),
complex(-1.11, +0.6);
      complex(0.37, +0.38), complex(0.19, -0.54), complex(-0.98, -0.36),
complex(0.22, -0.2);
      complex(0.83, +0.51), complex(0.2, +0.01), complex(-0.17, -0.46),
complex(1.47, +1.59);
      complex(1.08, -0.28), complex(0.2, -0.12), complex(-
0.070000000000000001, +1.23), complex(0.26, +0.26)];
b = [complex(1, +0), complex(0, +0), complex(-1, +0), complex(0, +0);
      complex(0, +0), complex(1, +0), complex(0, +0), complex(-1, +0)];
[k, l, aOut, bOut, alpha, beta, u, v, q, info] = f08vn(jobu, jobv, jobq,
a, b)

```

```

k =
      2
l =
      2
aOut =
    -2.7118          -1.4390 - 1.0315i   -0.0769 + 1.3613i   -0.2814 -
0.0324i      0          -1.8583          -1.0760 + 0.0310i    1.3292 +
0.3677i      0              0          3.2537          -0.0000 +
0.0000i      0              0              0          -2.1084
              0              0              0              0
              0              0              0              0
bOut =
      0              0          1.4142          -0.0000 +
0.0000i      0              0              0          -1.4142
      0              0              0          -1.4142
alpha =
    1.0000
    1.0000
    0.9006
    0.7417
beta =
      0
      0
    0.4346
    0.6707
u =
Columns 1 through 4
    -0.0130 - 0.3259i   -0.1404 - 0.2617i    0.2518 - 0.7979i   -0.0510 -
0.2175i
    0.4276 - 0.6258i    0.0863 - 0.0382i   -0.3219 + 0.1611i    0.1198 +
0.1632i
    -0.3259 + 0.1643i    0.3816 - 0.1822i    0.1323 - 0.0146i   -0.5067 +
0.1862i
    0.1591 - 0.0052i   -0.2821 + 0.1973i    0.2160 + 0.1881i   -0.4016 +
0.2679i
    -0.1721 - 0.0130i   -0.5094 - 0.5032i    0.0365 + 0.2032i    0.1927 +
0.1557i
    -0.2634 - 0.2477i   -0.1086 + 0.2847i    0.1091 - 0.1271i   -0.0882 +
0.5617i
Columns 5 through 6
    -0.0459 + 0.0001i   -0.0528 - 0.2249i
    -0.0803 - 0.4360i   -0.0381 - 0.2191i

```

	0.0597 - 0.5897i	-0.1385 - 0.0909i		
	-0.0464 + 0.3086i	-0.3735 - 0.5515i		
	0.5784 - 0.1244i	-0.0188 - 0.0557i		
	0.0158 + 0.0471i	0.6501 + 0.0049i		
v =				
	0.9893 + 0.0000i	-0.1146 + 0.0903i		
	-0.1146 - 0.0903i	-0.9893 + 0.0000i		
q =				
	0.7071	0	0.6995 + 0.0000i	0.0810 -
	0.0638i			
	0	0.7071	-0.0810 - 0.0638i	0.6995 -
	0.0000i			
	0.7071	0	-0.6995 - 0.0000i	-0.0810 +
	0.0638i			
	0	0.7071	0.0810 + 0.0638i	-0.6995 +
	0.0000i			
info =				
	0			